SM34165D				
Continuous Torque	9.67	in-lb		
	155	oz-in		
	1.09	N-m		
Peak Torque	14.12	in-lb		
	226	oz-in		
	1.60	N-m		
Nominal Continuous Power	235	Watt		
No Load Speed	3,100	RPM		
Max. Continuous Current* @ 2400 RPM	6.02	Amps		
Peak Power @ 1900 RPM	265	Watts		
Voltage Constant	14.98	V/kRPM		
Inductance	1.72	mH		
Encoder Resolution	8,000	Counts/Rev		
Rotor Inertia	0.014	oz-in-sec ²		
	9.890	10⁻⁵ Kg-m²		
Weight	5.0	lb		
	2.27	kg		
Shaft Diameter	0.375	in		
	9.53	mm		
Shaft, Radial Load	15	lb		
	6.80	kg		
Shaft, Axial Thrust Load	3	lb		
	1.36	kg		
DeviceNet Available	Yes			
PROFIBUS Available	Yes			
CANopen Available	Yes			
*Default voltage is 48V. See graphs for additional voltages.				



Operating temperature range: 0°C-85°C

Storage temperature range: -10°C-85°C, noncondensing

NOTE: Motor specifications are subject to changes without notice. Consult website and factory for latest data.

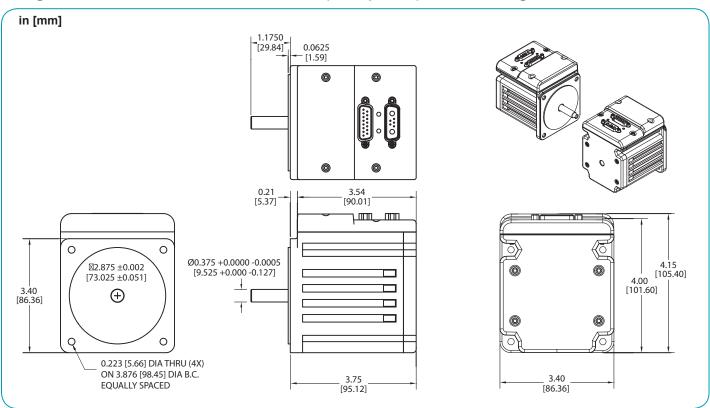


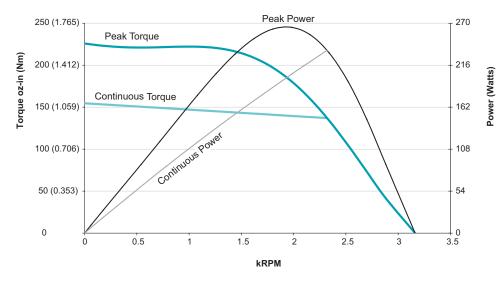




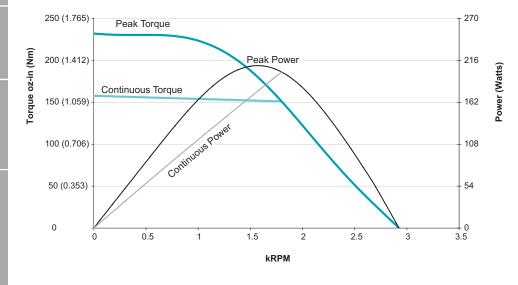
*Default voltage is 48V. See graphs for additional voltages.

Moog Animatics SmartMotor™ SM34165D (No Options) CAD Drawing

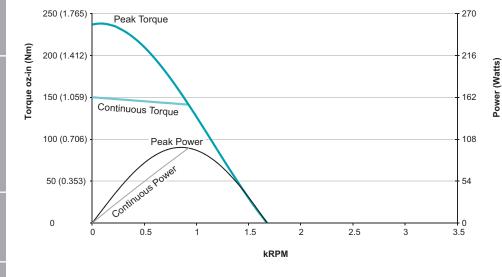




SM34165D at 48 VDC at rise to 85°C



SM34165D at 42 VDC at rise to 85°C



SM34165D at 24 VDC at rise to 85°C

All torque curves based on 25°C ambient.

Motors were operated using MDT
(Trapezoidal Drive Mode) Commutation.

For ambient temperatures above 25°C,
Continuous Torque must be linearly derated to 0% at 85°C.



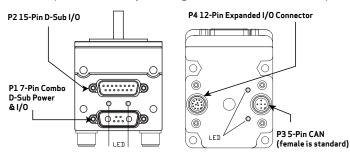
Class 5 D-Style Connector Pinouts

This table shows the pinouts for the connectors on the Class 5 D-style SmartMotors.

PIN	MAIN POWER	Specifications:	Notes:	P1
1	I/O - 6 GP, Index Input or "G" Command;	25 mAmp Sink or Source	Redundant connection on	
	For -CDS7, CAN-L only	10 Bit 0-5 VDC A/D	I/O connector	7W2 Combo
2	+5 VDC Out; For -CDS7, CAN-H only	50 mAmps Max (total)		D-Sub Connector
3	RS-232 Transmit	Com ch. 0	115.2 KBaud Max	
4	RS-232 Receive			0 02 00
5	Common Ground (typ. SIG Ground)	24.401/06	c NOTE	A1 3 4 5 A2
A1	Main Power	+24-48 VDC	See NOTE	
A2	Common Ground (req'd. POWER Ground)	6 : : : :	Must be Main Power Ground	P2
PIN	I/O CONNECTOR (5V TTL I/O)	Specifications:	Notes:	P2
1	I/O – 0 GP or Encoder A or Step Input		1.5 MHz Max as Encoder or Step Input	
2	I/O - 1 GP or Encoder B or Direction Input		1.5 MHz Max as Encoder or Direction Input	
3	I/O – 2 Positive Over Travel or GP	25 4 614 6		
4	I/O - 3 Negative Over Travel or GP	25 mAmp Sink or Source 10 Bit 0-5 VDC A/D		P2 DB-15 D-Sub Connector
5	I/O – 4 GP, IIC (SDA) or RS-485 A (Com ch. 1)		115.2 KBaud Max	8 7 6 5 4 3 2 1
6	I/O – 5 GP, IIC (SCL) or RS-485 B (Com ch.1)		115.2 KBaud Max	O (0000000) O
7	I/O - 6 GP, Index Input or "G" Command		Redundant connection on Main Power Connector	15 14 13 12 11 10 9
8	Phase A Encoder Output	24 mAmp Sink or Source		
9	Phase B Encoder Output	2 i manip strik di source		
10	RS-232 Transmit; For -CDS/7, CAN-L only	Com ch. 0	115.2 KBaud Max	
11	RS-232 Receive; For -CDS/7, CAN-H only		113.2 KBddd Max	
12	+5 VDC Out	50 mAmp Max (total)		
13	Common Ground (typ. SIG Ground)			
14	Common Ground	15050 6 . 10		
15	Main Power: +20-48 VDC	If DE Option, Control Power separate from Main Power	-	
	ports input impedance = 5 kohm (5 kohm pull-	,		D2
PIN	CAN bus	Connection:	Notes:	P3
1	NC	NC		M12 5-Pin
2	+V	NC except DeviceNet	Input current < 10 mA	Female
3	-V (ground, not common)	CAN Ground	Isolated	47
4	CAN-H	1 MBaud Max	15014124	3-50-1
				5
5	CAN-L	1 MBaud Max		2
PIN	Isolated 24 VDC I/O Connector	Max Load (sourcing)	Notes:	P4
1	I/O - 16 GP	8/		
2	/ I/O - 17 GP	150 mAmps		M12 12-Pin
3	I/O - 18 GP	150 mAmps		Female End View
4	I/O - 19 GP		These I/O ports also	Ella Fiell
5	I/O - 20 GP		support analog input	7 / 12
6	I/O - 21 GP		11	6×1/×8
7	I/O - 22 GP	300 mAmps		5 - 12 9
8	I/O - 23 GP			11-12321
9	I/O - 24 GP			4 10
10	I/O - 25 GP	1		3 2
11				
12	+24 Volts Input Ground-I/O (not common)	18-32 VDC	Isolated	

NOTE: These motors can operate on power down to +20 VDC, but it is not recommended due to greatly reduced performance — optimum performance is achieved at 48 VDC.

NOTE: All specifications are subject to change without notice. Consult the factory for the latest information.



CAUTION: Pins 14 and 15 are intended for use with DE series motors for control power only. Attempting to power a non-DE motor through those pins, as main servo-drive power, may result in immediate damage to the electronics, which will void the warranty.

CAUTION: Connectors P3 and P4 must be finger tightened only! DO NOT use a tool. Doing so can cause overtightening of the connection, which may damage the connector and will void the warranty.